## AMERICAN NATIONAL STANDARD

# Basic Nomenclature and <br> Definitions for Single-Point Cutting Tools 

ANSI B94.50-1975

REAFFIRMED 1995

FOR CURRENT COMMITTEE PERSONNEL
PLEASE SEE ASME MANUAL AS-11

SECRETARIAT
THE AMERICAN SOCIETY OF MECHANICAL ENGINEERS

No part of this document may be reproduced in any form, in an electronic retrieval system or otherwise, without the prior written permission of the publisher.

## FOREWORD

Technical Committee 2 on Tool Holder Shanks and Tool Post Openings was established under ASA Sectional Committee B5 on Small Tools and Machine Tool Elements in January 1926. In December 1946 it absorbed Technical Committee 19 on Single-Point Cutting Tools and its name was changed to Technical Committee 2 on Single-Point Tools and Tool Posts. This committee developed American Standard SinglePoint Tools and Tool Posts (ASA B5.22-1950), Section 1 of which covered terminology and definitions for single-point cutting tools. Late in 1955, Technical Committee 2 was subdivided into Groups A, B, and C, with Group C being responsible for nomenclature of Single-Point Tools. This Group became Technical Com Committee 16 on Nomenclature of Single-Point Tools in 1957, but remained inactive until January, 1962, when work on formulation of the present standard, as a revision of Section 1 of ASA B5.22-1950, was started. Later in 1962, ASA Sectional Committee B94 on Cutting Tools, Holders, Drivers, and Bushings was formed as an off-spring of Committee B5, and TC16 was included in its area of responsibility. In 1963, B94 Technical Committees were renumbered and TC16 became TC3. At the same time, its scope was broadened to cover "nomenclature of edges, faces, tool angles and their reference system, working angles and their reference system, for the working parts of cutting tools" and the name of the committee was changed to Technical Committee 3 on Basic Nomenclature of Cutting Tools. However, the committee decided to first complete the task of preparing a standard for single-point tools before proceeding to develop one applicable to all types of metal cutting tools. It is now undertaking preparation of the more general standard.

In September 1960, Technical Committee 29 of the International Standards Organization (ISO) had established Working Group 20 on Geometry of the Active Parts of Cutting Tools and this group became active in December 1962. Earlier in 1962, TC16 had begun cooperation with the committee dealing with cutting tool nomenclature of the British Standards Institution, to provide for harmonization of the U.S. and British efforts in this field. The United States agreed to participate in the ISO project and to be represented by members of TC16, or, on occasions when that was not possible, by the British delegation. The present standard is therefore the result of working closely with both ISO TC29 Working Group 20 and the British committee. It includes material which has already been the subject of international agreement in WG 20, set forth in Draft International standard ISO/DIS 3002. It also anticipates formal international agreement on various further aspects of the nomenclature and definitions. Some of these aspects will be dealt with in future revisions of this standard. However, it specifically omits nomenclature and definitions concerning the orientation and setting of the cutting tool in the machine tool (setting angles, etc.) since no international agreement on this subject has yet been reached. This subject will be included in later revisions of this standard when international agreement is arrived at.

To reach international agreement on all the aspects of nomenclature and definitions, some changes from accepted usage in the United States have been unavoidable. However, these changes have been small. It will be found that the agreement between this text and that of the corresponding British (draft) standard is very close.

This Standard was approved by the American National Standards Institute on October 10, 1975.

# AMERICAN NATIONAL STANDARDS COMMITTEE B94 Standardization of Cutting Tools, Holders, Drivers and Bushings 

(The following is the roster of the committee at the time of the approval of the standard)

## OFFICERS

Harry McLinden, Chairman<br>A. M. Mezey, Vice-Chairman

Kurt Wessely, Secretary

## STANDARDS COMMITTEE

## AMERICAN GEAR MANUFACTURERS ASSOCIATION, THE

P. M. Dean, Jr., Mechanical Technology, Inc., Latham, New York
G. L. Scott, Alternate, American Gear Manufacturer's Association, Washington, D.C.

AMERICAN SOCIETY OF MECHANICAL ENGINEERS, THE
M. E. Merchant, Cincinnati Milacron, Inc., Cincinnati, Ohio
G. M. Monacelli, General Electric Company, Detroit, Michigan
C. J. Oxford, Jr., National Twist Drill \& Tool Company, Rochester, Michigan
G. F. Wilson, A/ternate, Consultant, Wheeling, Illinois

CEMENTED CARBIDE PRODUCERS ASSOCIATION
W. E. Montgomery, Firth Sterling, Inc., McKeesport, Pennsylvania
A. P. Wherry, Alternate, Cemented Carbide Producers Association, Cleveland, Ohio

GENERAL SERVICES ADMINISTRATION
W. R. Wacker, General Services Administration, Washington, D.C.

HACK \& BAND SAW MANUFACTURERS ASSOCIATION OF AMERICA
Richard Schrade, Clemson Bros., Inc., Middletown, New York
J. E. Bates, Alternate, Hack \& Band Saw Manufacturers Association, Mt. Prospect, Illinois

METAL CUTTING TOOL INSTITUTE
W. A. Wagner, Cleveland Twist Drill Company, Cleveland, Ohio
R. M. Byrne, Alternate, Metal Cutting Tool Institute, New York, New York

NATIONAL ASSOCIATION OF PUNCH MANUFACTURERS
R. E. Smith, Dayton Progress Corporation, Dayton, Ohio

NATIONAL BUREAU OF STANDARDS
J. R. Pidgeon, National Bureau of Standards, Washington, D.C.

NATIONAL MACHINE TOOL BUILDERS' ASSOCIATION
G. F. Wilson, Consultant, Wheeling, Illinois
E. J. Loeffler, A/ternate, National Machine Tool Builders' Association, McLean, Virginia

SOCIETY OF AUTOMOTIVE ENGINEERS
To be appointed
SOCIETY OF CARBIDE ENGINEERS
C. H. Lang, c/o Society of Carbide Engincers, Bridgeville, Pennsylvania

SOCIETY OF MANUFACTURERS ENGINEERS
K. A. Lundell, The Producto Machine Company, Jamestown, New York
H. J. Moffatt, Bartonville, Illinois
W. N. Moore, The Ford Motor Company, Dearborn, Michigan

## TELEPHONE GROUP, THE

R. A. Agnew, Western Electric Company, Inc., Chicago, Illinois
S. P. Rogacki, Alternate, Western Electric Company, Inc., Kearney, New Jersey

## U.S. DEPT. OF THE AIR FORCE

To be appointed
U.S. DEPT. OF THE ARMY
D. L. York, Liaison, General Thomas J. Rodman Lab., Rock Island, Illinois
U.S. DEPT. OF THE NAVY
J. N. Cornette, Liaison, Naval Ship Systems Command, Washington, D.C.
U.S. MACHINE SCREW BUREAU

Herman Muenchinger, Continental Screw Company, New Bedford, Massachusetts
D. E. Chase, Alternate, Continental Screw Co., New Bedford, Massachusetts

INDIVIDUAL COMPANIES
Harold Cooper, Chrysler Corporation, Detroit, Michigan
William Hofbauer, Mohawk Tools, Inc., Montpelier, Ohio
Kenneth Hull, The Ingersoll Milling Machine Company, Rockford, Illinois
A. M. Mezey, Richards Brothers Punch Company, Detroit, Michigan

## INDIVIDUAL MEMBERS

Anderson Ashburn, American Machinist, New York, New York
Harry McLinden, Caterpillar Tractor Company, Peoria, Illinois

## TECHNICAL COMMITTEE 3

## Standardization of Basic Nomenclature for Cutting Tools

M. E. Merchant, Chairman, Director of Research Planning, Cincinnati Milacron Inc., Cincinnati, Ohio

Geoffrey Boothrovd, Professor, Department of Mechanical Engineering, University of Massachusetts, Amherst, Massachusetts
O. W. Boston, Professor, 56 Roslyn Road, Grosse Pointe Shores, Michigan

Joe H. Crawford, Group Supervisor, Standard Engineering, Sundstrand Machine Tool, Division of Sundstrand Corporation, Newburg Road, Belvidere, Illinois
Carl G. Erickson, Manager of Engineering, Cutting Tool and Gauge Division, Colt Industries, Pratt \& Whitney, Inc., West Hartford, Connecticut
K. H. Moltrecht, Industrial Press Inc., 200 Madison Avenue, New York, New York
G. Monacelli, Manager, Drafting Standards and Specifications, Metallurgical Products Department, General Electric Company, 11177 East Eight Mile Road, Detroit, Michigan
LeRoy A. Taylor, General Foreman, Plant Y12, Building 9212, Union Carbide Nuclear Company, Division of Union Carbide Corp., P.O. Box Y, Oak Ridge, Tennessee
Donald W. Warren, Engineering Standards Coordinator, Kennametal Inc., Latrobe, Pennsylvania
W. E. Stephens, Union Carbide Corp., Nuclear Division, Charlotte Hall Townsite, Oak Ridge, Tennessee

## CORRESPONDING MEMBERS

J. M. Galimberti, Kennametal Inc., Latrobe, Pennsylvania
W. L. Kennicott, Vice President, Kennametal Inc., Latrobe, Pennsylvania

Earl M. McCullough, Process \& Tool Engineering Department, John Deere East Moline Works, East Moline, Illinois
W. E. Montgomery, Teledyne Firth Sterling, P.O. Box 700, McKeesport, Pennsylvania
C. J. Oxford, Jr., Director of Research, National Twist Drill \& Tool Company, Rochester, Michigan

Robert M. Byrne, Technical Director, Metal Cutting Tool Institute, 331 Madison Ave., New York, New York

## CONTENTS

Page
Section

1. Scope ..... 1
2. Purpose ..... 1
3. Definition of a Single-Point Tool ..... 1
4. General Terms ..... 1
4.1 Surfaces on the Workpiece ..... 1
4.2 Tool Elements ..... 1
4.3 Tool Surfaces ..... 1
4.4 Cutting Edges ..... 2
4.5 Dimensions ..... 3
4.6 Tool and Workpiece Motions ..... 3
5. Reference Planes ..... 4
5.1 Background Information ..... 4
5.2 Tool-in-Hand System ..... 4
5.3 Tool-in-Use System ..... 5
6. Tool and Working Angles ..... 5
6.1 Background Information ..... 5
6.2 Tool Angles ..... 6
6.3 Working Angles ..... 7
Tables
Table 1 Symbols for Land Widths Associated with the Face and Flanks ..... 3
Table 2 Symbols for the Rake and Clearance on the Lands for the Major and Minor Cutting Edges ..... 6
Figures
Figure 1 Surfaces on the Workpiece ..... 8
Figure 2 Tool Elements, Tool Surfaces and Cutting Edges ..... 9
Figure 3 Chip Breaker ..... 10
Figure 4 Cutting Edges ..... 11
Figure 5 Corner Dimensions ..... 12
Figure 6 Tool Surfaces and Land Widths ..... 13
Figure 7 Tool and Workpicce Motions ..... 14
Figure 8 Tool-in-Hand Planes $P_{r}, P_{f}$ and $P_{p}$ for the Major Cutting Edge ..... 15
Figure 9 Tool-in-Hand Planes $P_{r}, P_{s}$ and $P_{n}$ for the Major Cutting Edge ..... 16
Figures(continued)
Figure 10 Tool-in-Hand Planes $\mathrm{P}_{\mathrm{f}}, \mathrm{P}_{\mathrm{s}}$ and $\mathrm{P}_{\mathrm{b}}$ for the Major Cutting Edge ..... 17
Figure 11 Tool-in-Hand Planes $P_{r}^{\prime}, P_{s}^{\prime}$ and $P_{n}^{\prime}$ for the Minor Cutting Edge ..... 18
Figure 12 Tool-in-Hand Planes $P_{r}$ and $P_{f}$ for the Major Cutting Edge of a Boring Tool ..... 19
Figure 13 Tool-in-Hand Planes $P_{r}$ and $P_{f}$ for the Major Cutting Edge of a Bent-Shank Planer Undercutting Tool ..... 20
Figure 14 Tool-in-Hand Planes $P_{r}$ and $P_{f}$ for the Major Cutting Edge of a Cut Off Tool ..... 21
Figure 15 Tool-in-Hand Planes $\mathrm{P}_{\mathrm{r}}$ and $\mathrm{P}_{\mathrm{f}}$ for the Major Cutting Edge of a Bent-Shank Facing Tool ..... 22
Figure 16 Tool-in-Hand Planes $P_{r}$ and $P_{f}$ for the Major Cutting Edge of a
Roller Turning Tool ..... 23
Figure 17 Tool-in-Use Planes $P_{r e}, P_{s e}, P_{o e}$ and $P_{n e}$ for the Major Cutting Edge ..... 24
Figure 18 Tool-in-Use Planes $\mathrm{P}_{\mathrm{re}}, \mathrm{P}_{\mathrm{fe}}$ and $\mathrm{P}_{\mathrm{pe}}$ for the Major Cutting Edge ..... 25
Figure 19 Tool Angles ..... 26
Figure 20 Tool Included Angle ..... 27
Figure 21 Tool Angles-Special Case Minor Cutting Edge Angles ..... 28
Figure 22 Working Angles ..... 29
Figure 23 Working Angles-Special Case Minor Cutting Edge Angles ..... 30
Appendix
A1. Summary of Angles ..... 31
A 1.1 Tool and Workpiece Motions ..... 31
A 1.2 Tool and Working Angles ..... 31
A2. List of Symbols ..... 33

## BASIC NOMENCLATURE AND DEFINITIONS FOR SINGLE-POINT CUTTING TOOLS

## 1. SCOPE

This American National Standard defines terms for certain basic features of single-point cutting tools; it deals with those features which are necessary to define the geometry of the cutting part.

The first main section (section 4) defines general terms applicable to single-point tools, including surfaces on the workpiece, tool elements, certain specific dimensions and tool and workpiece motions.

In the subsequent sections two systems of reference planes are defined with the aid of which socalled "tool angles" and "working angles" are defined. One system of reference planes is the "tool-inhand system"; this is used to define the geometry of the tool so that it can be manufactured and measured. The other system of reference planes, "the tool-in-use system", is required to define the effective geometry of the tool when it is actually performing a cutting operation.

## 2. PURPOSE

2.1 The purpose of this standard is to provide nomenclature, symbols and definitions of basic geometrical features, including angles, of single-point cutting tools.

## 3. DEFINITION OF A SINGLE-POINT TOOL

3.1 A single-point tool is a cutting tool having one cutting part (4.2.3) and one shank (4.2.1). They are commonly used in lathes, turret lathes, planers, shapers, boring mills and similar machine tools.

## 4. GENERAL TERMS

### 4.1 Surfaces on the Workpiece

4.1.1 Work Surface. The surface on the workpiece to be removed by machining. (Fig. 1)
4.1.2 Machined Surface. The desired surface produced by the action of the cutting tool. (Fig. 1)
4.1.3 Transient Surface. The part of the surface which is formed on the workpiece by the cutting edge (4.4.1) and removed during the following cutting stroke, during the following revolution of the tool or workpiece or, in other cases, as for example in a thread turning operation, during the following pass of the tool. (Fig. 1)

### 4.2 Tool Elements

4.2.1 Shank. That part of the tool by which it is held. (Fig. 2)
4.2.2 Tool Axis. An imaginary straight line with defined geometrical relationships to the locating surfaces used for the manufacture and sharpening of the tool and for holding the tool in use. Generally, the tool axis is the center line of the tool shank (4.2.1). (Fig. 2) It is usually parallel or perpendicular to the locating surface, although it could be the center line of a conical surface as in the case of a taper shank. When not obvious, the tool axis must be defined by the designer.
4.2.3 Cutting Part (Previously known as the "tool point".) The functional part of the tool comprised of the chip producing elements. The cutting edges (4.4.1), face (4.3.1), and flank (4.3.3) are therefore elements of the cutting part. (Fig. 2)
4.2.4 Base. A flat surface on the tool shank, parallel or perpendicular to the tool reference plane (5.2.1), useful for locating or orienting the tool in its manufacture, sharpening and measurement. (Fig. 2) Not all tools have a clearly defined base.
4.2.5 Wedge. The portion of the cutting part enclosed between the face (4.3.1) and the flank (4.3.3). It can be associated with either the major or minor cutting edge (4.4.1).

### 4.3 Tool Surfaces

Each tool surface is provided with a symbol consisting of $A$ with a suffix indicating the identity of the surface (e.g., $A_{\gamma}$, the face). When it is necessary
to distinguish clearly a surface associated with the minor cutting edge (4.4.1), the appropriate symbol bears a prime (e.g., $\mathrm{A}_{\alpha}{ }^{\prime}$, the minor flank).
4.3.1 Face $\left(A_{\gamma}\right)$. The surface or surfaces over which the chip flows (Fig. 2). When the face is composed of a number of surfaces inclined to one another, these are designated first face, second face, etc., starting from the cutting edge. These surfaces may be called lands and, unless otherwise specified, it is assumed that these are associated with the major cutting edge (4.4.1). Where it is necessary to distinguish the faces associated with the major and minor cutting edges (4.4.1), that part of the face which intersects the flank (4.3.3) to form the major cutting edge is called the major face and that part of the face which intersects the flank to form the minor cutting edge is called the minor face, for example, major first face, minor first face, etc.

### 4.3.2 Chip Breaker.

## NOTE

Pending international agreement on a definition of this term, the following definition is included for guidance:
A modification of the face, to control or break the chip, consisting of either an integral groove or an integral or attached obstruction. (Fig. 3)
4.3.3 Flank $\left(\mathrm{A}_{\alpha}\right)$. The tool surface or surfaces over which the surface produced on the workpiece passes. (Fig. 2). When the flank is composed of a number of surfaces inclined to one another, these are designated first flank, second flank, etc., starting from the cutting edge. These surfaces may be called lands and unless otherwise specified, it is assumed that these are associated with the major cutting edge (4.4.1). Where it is necessary to distinguish the flanks associated with the major and minor cutting edges (4.4.1), that part of the flank which intersects the face to form the major cutting edge is called the major flank and that part of the flank which intersects the face to form the minor cutting edge is called the minor flank, e.g. major first flank, minor first flank, etc.
4.4.1 Cutting Edge. That edge of the face which is intended to perform cutting.

The tool major cutting edge $S$ is that entire part of the cutting edge which commences at the point where the tool cutting edge angle $\kappa_{r}(6.2 .5)$ is zero and of. which at least a portion is intended to produce the transient surface (4.1.3) on the workpiece (Figs. 2 and 4). In the case of tools having a sharp corner (4.4.2) at which the value of $\kappa_{r}$ may be considered to pass through zero, the major cutting edge com-
mences at that corner. In the case of tools for which the value of $\kappa_{\mathrm{r}}$ does not decrease to zero at any point on the cutting edge, the entire cutting edge is the tool major cutting edge as, for example, in the case of a V-shaped threading tool.

The tool minor cutting edge $S$ ' is the remainder of the cutting edge, if any, and, where present, commences at the point on the cutting edge where $\kappa_{r}$ is zero but extends from this point in a direction away from the tool major cutting edge (Figs. 2 and 4). It is not intended to produce any of the transient surface (4.1.3) on the workpiece. Some tools may have more than one tool minor cutting edge as, for example, in the case of a cut-off tool.

The working major cutting edge $\mathrm{S}_{\mathrm{e}}$ is that entire part of the cutting edge which commences at the point where the working cutting edge angle $\kappa_{\mathrm{re}}(6.3 .5)$ is zero and of which at least a portion produces the transient surface (4.1.3) on the workpiece (Fig. 4). In the case of tools having a sharp corner (4.4.2) at which the value of $\kappa_{\mathrm{re}}$ may be considered to pass through zero, the working major cutting edge commences at that corner. In the case of tools for which the value of $\kappa_{\text {re }}$ does not decrease to zero at any point on the cutting edge, the entire cutting edge is the working major cutting edge as, for example, in the case of a $V$-shaped threading tool.

The working minor cutting edge $\mathrm{S}_{\mathrm{e}}{ }^{\prime}$ is the remainder of the cutting edge, if any, and, where present, commences at the point on the cutting edge where $\kappa_{r e}$ is zero but extends from this point in a direction away from the working major cutting edge (Fig. 4). It does not produce any of the transient surface (4.1.3) on the workpiece. Some tools may have more than one working minor cutting edge as, for example, in the case of a cut-off tool.

A distinction must be made between the tool major cutting edge and the working major cutting edge because the points at which $\kappa_{r}$ and $\kappa_{r e}$ can be considered to be zero are not, in general, coincident.
4.4.2 Corner (Previously known as the "nose".) The relatively small portion of the cutting edge at the junction of the major and minor cutting edges; it may be curved, straight, or the actual intersection of these cutting edges. (Figs. 2 and 5).
4.4.3 Rounded Corner. A corner having a curved cutting edge. (Fig. 5).
4.4.4 Chamfered Corner. A corner having a straight cutting edge. (Fig. 5).
4.4.5 Selected Point on the Cutting Edge. A point selected on any part of the cutting edge in order to define, for example, the tool or working angles ( 6.2
or 6.3 ) at that point. The selected point may be on the major cutting edge or on the minor cutting edge. When the selected point is so chosen as to be on the minor cutting edge, the planes and angles associated with this point are so designated (5.1.3, 5.1.4, 6.1.4 and 6.1.5). (Figs. 7 through 23).
4.4.6 Rounded Cutting Edge. A cutting edge which is formed by a rounded transition between the face $\mathrm{A}_{\boldsymbol{\gamma}}$ and the flank $\mathrm{A}_{\alpha}$.

### 4.5 Dimensions

### 4.5.1 Feed (f).

NOTE
Pending international agreement on a definition of this term, the following definition is included for guidance:
The displacement of the tool relative to the workpiece, in the direction of feed motion (4.6.3), per stroke or per revolution of the workpiece or tool.
4.5.2 Back Engagement ( $\mathrm{a}_{\mathrm{p}}$ ) (Previously known as the depth of cut).

NOTE
Pending international agreement on a definition of this term, the following definition is included for guidance:
The instantaneous engagement of the tool with the workpiece, measured perpendicular to the working plane $\mathrm{P}_{\mathrm{fe}}$ (5.3.2). (Fig. 4).
4.5.3 Corner Radius ( $\mathrm{r}_{\epsilon}$ ). The nominal radius of a rounded corner (4.4.3) measured in the tool reference plane $\mathrm{P}_{\mathrm{r}}$ (5.2.1). (Fig. 5).
4.5.4 Chamfered Corner Length $\left(b_{\epsilon}\right)$. The nominal length of a chamfered corner (4.4.4) measured in the tool reference plane $\mathrm{P}_{\mathrm{r}}$ (5.2.1). (Fig. 5).
4.5.5 Land Width ( $b_{\gamma}$ and $b_{\alpha}$ ). The width of a land on the major face (4.3.1) is designated by $b_{\gamma}$, and the width of a land on the minor face (4.3.1) is designated by $\mathrm{b}^{\prime}$. The width of a land on the major flank (4.3.3) is designated by $b_{\alpha}$. The identification
number of the land, together with the suffix used to identify the plane of measurement, may be added if necessary, e.g., $b_{\gamma \mathrm{n} 2}{ }^{\prime} b_{\alpha_{n 1}}{ }^{\prime} b_{o m 2^{\prime}}$. (See Fig. 6 and Table 1)
4.5.6 Rounded Cutting Edge Radius ( $r_{n}$ ). The nominal radius of a rounded cutting edge measured in the cutting edge normal plane $\mathrm{P}_{\mathrm{n}}$ (5.2.6).

### 4.6 Tool and Workpiece Motions

4.6.1 Primary Motion. (All motions, directions of motions and speeds are defined relative to the workpiece.) The main motion provided by a machine tool or manually to cause relative motion between the tool and the workpiece so that the face of the tool approaches the workpiece material. In a lathe, this motion is provided by the rotary motion of the workpiece; in a planing machine it is provided by the longitudinal motion of the table. In the case of a screw cutting operation in a lathe, the primary motion is considered to be helical rather than purely rotary. Usually, the primary motion absorbs most of the total power required to perform a machining operation.
4.6.2 Direction of Primary Motion. The direction of instantaneous primary motion of the selected point on the cutting edge (4.4.5) relative to the workpiece. (Fig. 7).
4.6.3 Feed Motion. A motion which may be provided to the tool or workpiece by a machine tool or manually which, when added to the primary motion, leads to a repeated or continuous chip removal and the creation of a machined surface with the desired geometric characteristics. This motion may proceed by steps or continuously; in either case it usually absorbs a small proportion of the total power required to perform a machining operation.
4.6.4 Direction of Feed Motion. The direction of instantaneous feed motion of the selected point on the cutting edge (4.4.5) relative to the workpiece. (Fig. 7).

Table 1, Symbols for Land Widths associated with the Face and Flanks

| TOOL SURFACE | PLANE OF MEASUREMENT | FIRST LAND <br> WIDTH | SECOND LAND <br> WIDTH | THIRD LAND <br> WIDTH |
| :--- | :--- | :---: | :---: | :---: |
| Face $A_{\gamma}$ | Cutting edge normal plane $P_{n}$ <br> Flank $A_{\alpha}$ <br> Minor flank $A_{\alpha}{ }^{\prime}$ | Cutting edge normal plane $P_{n}$ <br> Minor cutting edge normal <br> plane $P_{n}{ }^{\prime}$ <br> $b_{\alpha n 1}$ | $b_{\gamma n 2}$ | $b_{\gamma n 3}$ |

4.6.5 Resultant Cutting Motion. The motion resulting from simultaneous primary motion and feed motion.
4.6.6 Resultant Cutting Direction. The direction of the instantaneous resultant cutting motion of the selected point on the cutting edge (4.4.5) relative to the workpiece. (Fig. 7).
4.6.7 Cutting Speed (v). The instantaneous velocity of the primary motion (4.6.1) of the selected point on the cutting edge (4.4.5) relative to the workpiece. (Fig. 7).
4.6.8 Feed Speed ( $\mathrm{v}_{\mathrm{f}}$ ). The instantaneous velocity of the feed motion (4.6.3) of the selected point on the cutting edge (4.4.5) relative to the workpiece (Fig. 7). When the feed is intermittent, for example, in the case of a planing operation, the feed speed is not defined.
4.6.9 Resultant Cutting Speed ( $\mathrm{v}_{\mathrm{e}}$ ). The instantaneous velocity of the resultant cutting motion (4.6.5) of the selected point on the cutting edge (4.4.5) relative to the workpiece. (Fig. 7).
4.6.10 Feed Motion Angle ( $\phi$ ). The angle between the directions of simultaneous feed motion (4.6.4) and primary motion (4.6.2). It is therefore measured in the working plane $\mathrm{P}_{\mathrm{fe}}$ (5.3.2) (Fig. 7). In certain machining operations such as planing and shaping this angle cannot be defined.
4.6.11 Resultant Cutting Speed Angle ( $\eta$ ). The angle between the direction of primary motion (4.6.2) and the resultant cutting direction (4.6.6). It is therefore measured in the working plane $\mathrm{P}_{\mathrm{fe}}$ (5.3.2). (Fig. 7).

## 5. REFERENCE PLANES

### 5.1 Background Information.

5.1.1 Reference systems of planes are necessary for defining and specifying the angles of a cutting tool. One system (the tool-in-hand system) is needed for defining the geometry of the tool for its manufacture and measurement. A second system (the tool-inuse system) is needed for specifying the geometry of the cutting tool when it is performing a cutting operation.*

[^0]5.1.2 The planes defined in the first system are termed tool-in-hand planes; their titles, with two exceptions (5.2.2 and 5.2.6) each include the word "tool". The planes defined in the second system are termed "tool-in-use" planes; their titles, with one exception (5.3.6) all include the word "working".
5.1.3 Since the angles and other geometric features vary from point to point along the cutting edge of a tool, it is necessary to locate the reference system at whatever point one desires to be able to define the tool geometry. Each plane is therefore defined with respect to a selected point on the cutting edge (4.4.5). The title of the plane may include an indication of whether the selected point is located on the major or minor cutting edge. For example, at a selected point on the minor cutting edge the corresponding plane is termed the tool minor cutting edge plane.
5.1.4 Each plane is provided with a symbol consisting of $P$ with a suffix indicating the plane's identity [e.g., $P_{s}$, the tool cutting edge plane (5.2.4)]. For the planes defined below, the selected point on the cutting edge is considered to be located on the major cutting edge. When it is necessary to distinguish clearly a plane passing through a selected point on the minor cutting edge, the appropriate symbol bears a prime (e.g., $\mathrm{P}_{\mathrm{s}}$, the tool minor cutting edge plane).
5.1.5 When the cutting edge, face or flank is curved, the tangents or tangential planes through the selected point should be used in the reference systems of planes.
5.1.6 The symbol used for a plane in the tool-inuse system bears the additional suffix "e", for "effective" [e.g., $P_{\text {se }}$, the working cutting edge plane (5.3.4)] to distinguish it from the corresponding tool-in-hand plane [e.g., $P_{s}$, the tool cutting edge plane (5.2.4)]

### 5.2 Tool-in-Hand System

5.2.1 Tool Reference Plane ( $\mathrm{P}_{\mathrm{r}}$ ). A plane through the selected point on the cutting edge, so chosen as to be either parallel or perpendicular to a plane or axis of the tool convenient for locating or orienting the tool for its manufacture, sharpening or measurement.

The plane must be chosen and defined for each individual type of cutting tool so that it meets the conditions prescribed above and is generally oriented perpendicular to the assumed direction of primary motion (4.6.2). (Figs. 8, 9, 12).

For ordinary lathe, planer and shaper tools it is a
plane parallel to the base (4.2.4) of the tool. (Figs. 8, $9,10,11,13$ and 14).

For a vertical shank or tangential tool or for a horizontal shank planer tool it is a plane perpendicular to the tool axis (4.2.2). (Fig. 16).
5.2.2 Assumed Working Plane ( $\mathrm{P}_{\mathrm{f}}$ ). A plane through the selected point on the cutting edge, perpendicular to the tool reference plane $P_{r}$ and so chosen as to be either parallel or perpendicular to a plane or axis of the tool convenient for locating or orienting the tool for its manufacture, sharpening or measurement.

This plane must be chosen and defined for each individual type of cutting tool so that it meets the conditions prescribed above and is generally oriented parallel to the assumed direction of feed motion (4.6.4). (Figs. 8, 10, 12, 16).

For ordinary turning, planing, shaping, or similar tools it is a plane perpendicular to the tool axis. (Figs. 8 and 13).

For a cut-off tool and most facing tools it is a plane parallel to the tool axis. (Figs. 14 and 15).
5.2.3 Tool Back Plane ( $\mathrm{P}_{\mathrm{p}}$ ). A plane through the selected point on the cutting edge and perpendicular both to the tool reference plane $\mathrm{P}_{\mathrm{r}}$ and to the assumed working plane $P_{f}$. (Fig. 8).
5.2.4 Tool Cutting Edge Plane $\left(\mathrm{P}_{\mathrm{s}}\right)$. A plane tangent to the cutting edge at the selected point and perpendicular to the tool reference plane $\mathrm{P}_{\mathrm{r}}$. (Figs. 9, 10 and 11).
5.2.5 Tool Flank Orthogonal Plane $\left(\mathrm{P}_{\mathrm{b}}\right)$. A plane through the selected point on the cutting edge, perpendicular both to the flank $\mathrm{A}_{\alpha}$ and to the tool reference plane $P_{r}$. (Fig. 10).
5.2.6 Cutting Edge Normal Plane ( $\mathrm{P}_{\mathrm{n}}$ ). A plane perpendicular to the cutting edge at the selected point on the cutting edge. (Figs. 9 and 11).

### 5.3 Tool-in-Use System

5.3.1 Working Reference Plane ( $\mathrm{P}_{\mathrm{re}}$ ). A plane through the selected point on the cutting edge and perpendicular to the resultant cutting direction (4.6.6). (Figs. 17 and 18).

[^1]5.3.2 Working Plane $\left(\mathrm{P}_{\mathrm{fe}}\right)$. A plane through the selected point on the cutting edge and containing both the direction of primary motion (4.6.2) and the direction of feed motion (4.6.4). This plane is thus perpendicular to the working reference plane $\mathrm{P}_{\mathrm{re}}$. (Figs. 7 and 18).
5.3.3 Working Back Plane ( $\mathrm{P}_{\mathrm{pe}}$ ). A plane through the selected point on the cutting edge and perpendicular both to the working reference plane $\mathrm{P}_{\mathrm{re}}$ and to the working plane $\mathrm{P}_{\mathrm{fe}}$. (Fig. 18).
5.3.4 Working Cutting Edge Plane ( $\mathrm{P}_{\mathrm{se}}$ ). A plane tangent to the cutting edge at the selected point and perpendicular to the working reference plane $P_{r e}$. This plane thus contains the resultant cutting direction (4.6.6). (Fig. 17).
5.3.5 Working Orthogonal Plane* $\left(\mathrm{P}_{\mathrm{oe}}\right)$. A plane through the selected point on the cutting edge and perpendicular both to the working reference plane $P_{r e}$ and to the working cutting edge plane $\mathrm{P}_{\text {se }}$. (Fig. 17).
5.3.6 Cutting Edge Normal Plane ( $\mathrm{P}_{\mathrm{n} e}$ ). The cutting edge normal plane in the tool-in-use system is identical with the cutting edge normal plane defined in the tool-in-hand system; $\mathrm{P}_{\mathrm{ne}} \equiv \mathrm{P}_{\mathrm{n}}$ (5.2.6). (Fig. 17).

## 6. TOOL AND WORKING ANGLES

### 6.1 Background Information

6.1.1 The angles are necessary for the determination of the geometrical position of the tool cutting edge, the face and the flank.
6.1.2 One set of angles is needed for defining the angles of the tool as an entity in itself, that is, for the tool-in-hand; these angles are designated tool angles and, with one exception (6.2.8), have the prefix "tool" in their titles. These angles are necessary for manufacturing, sharpening or measuring the tool.
6.1.3 A second set of angles is needed for defining the angles which affect the action of the tool in the cutting process, that is, for the tool-in-use; these angles are designated working angles and have the prefix "working" in their titles.
6.1.4 Since tool and working angles vary from point to point along the cutting edge, the definitions of the angles given below refer always to the angles at the selected point (4.4.5). When the cutting edge, face or flank is curved, the tangents or tangential planes through the selected point are employed in the reference systems of planes used to define the angles (5.1.5).
6.1.5 Each angle is specified, where appropriate, with reference to a particular cutting edge on the tool, depending on the location of the selected point on the cutting edge. The title of the angle may include an indication of whether the selected point is located on the major or minor cutting edge. For example, at a selected point on the major cutting edge there is the tool normal rake (6.2.1) and at a selected point on the minor cutting edge, the corresponding angle is termed the tool minor cutting edge normal rake.
6.1.6 Each angle is provided with a symbol consisting of a Greek letter with a suffix indicating the plane in which the angle is measured [e.g., $\gamma_{\mathrm{n}}$, the tool normal rake (6.2.1)]. For the angles defined below, the selected point on the cutting edge is considered to be located on the major cutting edge. When it is necessary to distinguish clearly angles defined with respect to a selected point on the minor cutting edge, the appropriate symbol bears a prime (e.g., $\gamma_{n}{ }^{\prime}$, the tool minor cutting edge normal rake).
6.1.7 The symbol used for a working angle bears the additional suffix "e" for "effective", [e.g., $\gamma_{\text {ne }}$, the working normal rake (6.3.1)] to distinguish it from the corresponding tool angle [e.g., $\gamma_{n}$, the tool normal rake (6.2.1)].
6.1.8 When the face or flank is composed of a number of surfaces inclined to one another, these surfaces are numbered consecutively, starting from the cutting edge. The number of the land is used as an additional suffix to the appropriate symbols to associate the rake or clearance angle with its particular land (e.g., $\gamma_{n 1}, \gamma_{n 2 e}-$ See Table 2 and Fig. 6). When the face or flank has only one surface, the suffixes 1 , 2 , etc., are not used.

[^2]6.1.9 The signs of the various angles are defined, where necessary, in the appropriate figures.

### 6.2 Tool Angles.

The tool angles are defined with the aid of the tool-in-hand reference system of planes defined in section 5.2.

The sum of the tool normal clearance (6.2.2), the normal wedge angle (6.2.8) and the tool normal rake (6.2.1) is equal to $90^{\circ}$.

In practice, the tool normal rake, tool normal clearance and tool cutting edge inclination (6.2.6) are usually acute angles.
6.2.1 Tool Normal Rake $\left(\gamma_{n}\right)$. The angle between the face $A_{\gamma}$ and the tool reference plane $P_{r}$ measured in the cutting edge normal plane $P_{n}$. (Figs. 19 and 21)
6.2.2 Tool Normal Clearance $\left(\alpha_{n}\right)$. The angle between the flank $A_{a}$ and the tool cutting edge plane $P_{s}$ measured in the cutting edge normal plane $P_{n}$. (Figs. 19 and 21)
6.2.3 Tool Base Clearance $\left(\alpha_{\mathrm{h}}\right)$. The angle between the flank $A_{\alpha}$ and the tool cutting edge plane $P_{s}$ measured in the tool flank orthogonal plane $\mathbf{P}_{\mathrm{b}}$. (Figs. 19 and 21)
6.2.4 Tool Lead Angle (Tool Approach Angle*) $\left(\psi_{\mathrm{r}}\right)$. The angle between the tool cutting edge plane $P_{s}$ and the tool back plane $P_{p}$ measured in the tool reference plane $P_{r}$. (Fig. 19). $\psi_{r}$ is defined only for the major cutting edge.
6.2.5 Tool Cutting Edge Angle ( $\kappa_{\mathrm{r}}$ ). The angle between the tool cutting edge plane $P_{s}$ and the assumed working plane $P_{f}$ measured in the tool reference plane $\mathrm{P}_{\mathrm{r}}$ (Figs. 19 and 21). Thus at any selected point on the major cutting edge the sum of $\psi_{\mathrm{r}}$ and $\kappa_{\mathrm{r}}$ is always $90^{\circ}$.

Table 2, Symbols for the Rake and Clearance on the Lands for the Major and Minor Cutting Edges

|  | $\begin{aligned} & \text { NO } \\ & \text { LAND } \end{aligned}$ | WITH LANDS |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  | First Face or Flank | Second Face or Flank | Third Face or Flank |
| Tool Normal Rake | $\gamma_{n}$ | $\gamma_{n 1}$ | $\gamma_{n 2}$ | $\gamma_{\text {n3 }}$ |
| Tool Minor Cutting Edge Normal Rake | $\gamma_{n}{ }^{\prime}$ | $\gamma_{\mathrm{n} 1}{ }^{\prime}$ | $\gamma_{\mathrm{n} 2}{ }^{\prime}$ | $\gamma_{n 3}{ }^{\prime}$ |
| Tool Normal Clearance | $\alpha_{n}$ | $\alpha_{n 1}$ | $\alpha_{n 2}$ | $\alpha_{\text {n3 }}$ |
| Tool Minor Cutting Edge Normal Clearance | $\alpha_{n}{ }^{\prime}$ | $\alpha_{n 1}{ }^{\prime}$ | $\alpha_{n 2}{ }^{\prime}$ | $\alpha_{n 3}{ }^{\prime}$ |

6.2.6 Tool Cutting Edge Inclination ( $\lambda_{s}$ ). The angle between the cutting edge $S$ and the tool reference plane $P_{r}$ measured in the tool cutting edge plane $P_{s}$. (Figs. 19 and 21)
6.2.7 Tool Included Angle ( $\epsilon_{\mathrm{r}}$ ). The angle between the tool cutting edge plane $P_{s}$ and the tool minor cutting edge plane $\mathrm{P}_{\mathrm{s}}$ ' measured in the tool reference plane $\mathrm{P}_{\mathrm{r}}$. (Fig. 20). Thus $\kappa_{\mathrm{r}}+\epsilon_{\mathrm{r}}+\kappa_{\mathrm{r}}{ }^{\prime}=180^{\circ}$.

## NOTE

This definition assumes the use of two selected points, one on the major cutting edge and one on the minor cutting edge.
6.2.8 Normal Wedge Angle $\left(\beta_{\mathrm{n}}\right)$. The included angle between the face $\mathrm{A}_{\gamma}$ and the flank $\mathrm{A}_{\alpha}$ measured in the cutting edge normal plane $\mathrm{P}_{\mathrm{n}}$. (Figs. 19 and 21)

### 6.3 Working Angles

The working angles are defined with the aid of the tool-in-use reference system of planes specified in Section 5.3.

The sum of the working normal clearance (6.3.2), the normal wedge angle (6.3.7) and the working normal rake (6.3.1) is equal to $90^{\circ}$.

In practice, the working normal rake, working normal clearance and working cutting edge inclination (6.3.6) are usually acute angles.

[^3]6.3.1 Working Normal Rake $\left(\gamma_{\mathrm{ne}}\right)$. The angle between the face $A_{\gamma}$ and the working reference plane $P_{r e}$ measured in the cutting edge normal plane $P_{n e}$ (Figs. 22 and 23). (Note that $\mathrm{P}_{\mathrm{ne}} \equiv \mathrm{P}_{\mathrm{n}}$ )
6.3.2 Working Normal Clearance ( $\alpha_{\text {ne }}$ ). The angle between the flank $\mathrm{A} \alpha$ and the working cutting edge plane $P_{s e}$ measured in the cutting edge normal plane $P_{\text {ne }}$. (Figs. 22 and 23)
6.3.3 Working Orthogonal Clearance* $\left(\alpha_{\text {oe }}\right)$. The angle between the flank $\mathrm{A}_{\alpha}$ and the working cutting edge plane $\mathrm{P}_{\text {se }}$ measured in the working orthogonal plane $\mathrm{P}_{\mathrm{oe}}$. (Figs. 22 and 23)
6.3.4 Working Lead Angle (Working Approach Angle**) ( $\psi_{\mathrm{re}}$ ). The angle between the working cutting edge plane $P_{\text {se }}$ and the working back plane $P_{p e}$ measured in the working reference plane $P_{r e}$. (Fig. 22). $\psi_{\mathrm{re}}$ is defined only for the major cutting edge.
6.3.5 Working Cutting Edge Angle ( $\kappa_{\text {re }}$ ). The angle between the working cutting edge plane $P_{\text {se }}$ and the working plane $\mathrm{P}_{\mathrm{fe}}$ measured in the working reference plane $\mathrm{P}_{\mathrm{re}}$. (Figs. 22 and 23). Thus, at any selected point on the major cutting edge, the sum of $\kappa_{\text {re }}$ and $\psi_{\text {re }}$ is always $90^{\circ}$.
6.3.6 Working Cutting Edge Inclination ( $\lambda_{\text {se }}$ ). The angle between the working cutting edge $\mathrm{S}_{\mathrm{e}}$ and the working reference plane $P_{\mathrm{re}}$ measured in the working cutting edge plane $\mathrm{P}_{\mathrm{se}}$. (Figs. 22 and 23)
6.3.7 Normal Wedge Angle ( $\beta_{\mathrm{ne}}$ ). The normal wedge angle in the tool-in-use system is identical with the normal wedge angle defined in the tool-in-hand system and $\beta_{\mathrm{ne}} \equiv \beta_{\mathrm{n}}$ (6.2.8). (Fig. 22).


FIG. 1 SURFACES ON THE WORKPIECE


FIG. 2 TOOL ELEMENTS, TOOL SURFACES AND CUTTING EDGES


FIG. 3 CHIP BREAKER


VIEW ON TOOL REFERENCE PLANE, Pr (PARALLEL TO TOOL BASE)

VIEW ON WORKING REFERENCE PLANE, $\mathrm{P}_{\text {re }}$ (PERPENDICULAR TO RESULTANT CUTTING DIRECTION)

Fig. 4 cutting edges

SHARP CORNER

VIEW ON TOOL REFERENCE PLANE $\mathrm{P}_{\mathrm{r}}$


FIG. 5 CORNER DIMENSIONS


SECTIONAL VIEW ON CUTTING EDGE NORMAL PLANE $P_{n}$

FIG. 6 TOOL SURFACES \& LAND WIDTHS


FIG. 7 TOOL AND WORKPIECE MOTIONS


FIG. 8 TOOL-IN-HAND PLANES $P_{r} . P_{f}$ AND $P_{p}$ FOR THE MAJOR CUTTING EDGE


FIG. 9 TOOL-IN-HAND PLANES $P_{r}, P_{s}$ AND $P_{\mathrm{n}}$ FOR THE MAJOR CUTTING EDGE


VIEW ON TOOL REFERENCE PLANE, $P_{r}$

FIG. 10 TOOL-IN-HAND PLANES $\mathrm{P}_{\mathrm{f}}, \mathrm{P}_{\mathrm{s}}$ AND $\mathrm{P}_{\mathrm{b}}$ FOR THE MAJOR CUTTING EDGE


FIG. 11 TOOL-IN-HAND PLANES Pr', $P_{s}^{\prime}$ AND $P_{n}^{\prime}$ FOR THE MINOR CUTTING EDGE


FIG. 12 TOOL-IN-HAND PLANES Pr AND Pf FOR THE MAJOR CUTTING EDGE OF A BORING TOOL


ASSUMED WORKING PLANE (PERPENDICULAR
TO TOOL REFERENCE PLANE, $P_{r}$ AND PERPENDICULAR TO TOOL AXIS)

FIG. 13 TOOL-IN-HAND PLANES $P_{r}$ AND $P_{f}$ FOR THE MAJOR CUTTING EDGE OF A BENT-SHANK PLANER UNDERCUTTING TOOL


FIG. 14 TOOL-IN-HAND PLANES Pr AND Pf FOR THE MAJOR CUTTING EDGE OF A CUT-OFF TOOL


FIG. 15 TOOL-IN-HAND PLANES $P_{r}$ AND $P_{f}$ FOR THE MAJOR CUTTING EDGE OF A BENT SHANK FACING TOOL


FIG. 16 TOOL-IN-HAND PLANES $P_{r}$ AND $P_{f}$ FOR THE MAJOR CUTTING EDGE OF A ROLLER TURNING TOOL


FIG. 17 TOOL-IN-USE PLANES $P_{\text {re }}, P_{\text {se }}, P_{\text {oe }}$ AND $P_{\text {ne }}$ FOR THE MAJOR CUTTING EDGE


FIG. 18 TOOL-IN-USE PLANES $P_{r e}$. $\mathrm{P}_{\mathrm{fe}}$ AND $\mathrm{P}_{\mathrm{pe}}$ FOR THE MAJOR CUTTING EDGE


FIG. 19 TOOL ANGLES


FIG. 20 TOOL INCLUDED ANGLE


FIG. 21 TOOL ANGLES-SPECIAL CASE MINOR CUTTING EDGE ANGLES


FIG. 22 WORKING ANGLES


FIG. 23 WORKING ANGLES-SPECIAL CASE MINOR CUTTING EDGE ANGLES

## APPENDIX A

## A1. SUMMARY OF ANGLES

## A1.1 Tool and Workpiece Motions

| DEFINITION <br> NO. | ANGLE | DEFINITION |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  | Angle <br> between | and | measured <br> in plane |
| 4.6 .10 | Feed motion <br> angle $\phi$ | direction of <br> feed motion | direction of <br> primary <br> motion | $\mathrm{P}_{\mathrm{fe}}$ |
| 4.6 .11 | Resultant cut- <br> ting speed <br> angle $\eta$ | Direction of <br> primary <br> motion | resultant cut- <br> ting direction | $\mathrm{P}_{\mathrm{fe}}$ |

A1.2 Tool and Working Angles

| DEFINITION NO. | ANGLE |  | DEFINITION |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | Tool Angle | Working Angle | Angle between | and | measured in plane |
| 6.2.1 | Tool normal rake $\gamma_{n}$ |  | $\mathrm{A}_{\boldsymbol{\gamma}}$ | $\mathrm{P}_{\mathrm{r}}$ | $P_{n}$ |
| 6.3.1 |  | Working normal rake $\gamma_{\text {ne }}$ | $\mathrm{A}_{\gamma}$ | $\mathrm{Pre}_{\text {re }}$ | $P_{n e}\left(\equiv P_{n}\right)$ |
| 6.2.2 | Tool normal clearance $\alpha_{n}$ |  | $\mathrm{A}_{\alpha}$ | $\mathrm{P}_{\text {s }}$ | $P_{n}$ |
| 6.3.2 |  | Working normal clearance $\alpha_{\text {ne }}$ | $\mathrm{A}_{\alpha}$ | $\mathrm{P}_{\text {se }}$ | $\mathrm{P}_{\mathrm{ne}}\left(\equiv \mathrm{P}_{n}\right)$ |
| 6.2.3 | Tool base clearance $\alpha_{a}$ |  | $\mathrm{A}_{\alpha}$ | $\mathrm{P}_{\text {s }}$ | $\mathrm{P}_{\mathrm{b}}$ |
| 6.3.3 |  | Working orthogonal clearance $\alpha_{\text {oe }}$ | $\mathrm{A}_{\alpha}$ | $\mathrm{P}_{\text {se }}$ | $\mathrm{P}_{\text {oe }}$ |

A1.2 Tool and Working Angles (Continued)

| DEFINITIONNO. | ANGLE |  | DEFINITION |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | Tool Angle | Working Angle | Angle between | and | measured in plane |
| 6.2.4 | Tool lead angle $\psi_{r}$ (Tool approach angle) (Applies only to major cutting edge) |  | $\mathrm{P}_{\text {s }}$ | $\mathrm{P}_{\mathrm{p}}$ | $\mathrm{P}_{\mathrm{r}}$ |
| 6.3.4 |  | Working lead angle $\psi_{\mathrm{re}}$ (Working approach angle) (Applies only to major cutting edge) | $\mathrm{P}_{\text {se }}$ | $\mathrm{P}_{\mathrm{pe}}$ | $\mathrm{P}_{\mathrm{re}}$ |
| 6.2.5 | Tool cutting edge angle $\kappa_{r}$ |  | $\mathrm{P}_{\text {s }}$ | $\mathrm{P}_{\mathrm{f}}$ | $\mathrm{P}_{\mathrm{r}}$ |
| 6.3.5 |  | Working cutting edge angle $\kappa_{\mathrm{re}}$ | $\mathrm{P}_{\text {se }}$ | $\mathrm{P}_{\mathrm{fe}}$ | $\mathrm{Pr}_{\mathrm{re}}$ |
| 6.2.6 | Tool cutting edge inclination $\lambda_{s}$ |  | S | $\mathrm{P}_{\mathrm{r}}$ | $\mathrm{P}_{\text {s }}$ |
| 6.3.6 |  | Working cutting edge inclination $\lambda_{\text {se }}$ | $\mathrm{S}_{\text {e }}$ | $\mathrm{Pr}_{\mathrm{re}}$ | $\mathrm{P}_{\text {se }}$ |
| 6.2.7 | Tool included angle $\epsilon_{\mathrm{r}}$ |  | $\mathrm{P}_{\text {s }}$ | $\mathrm{P}^{\prime}$ | $\mathrm{P}_{\mathrm{r}}$ |
| $\begin{aligned} & 6.2 .8 \\ & 6.3 .7 \end{aligned}$ | Normal wedge angle $\beta_{n}\left(\equiv \beta_{\mathrm{ne}}\right.$ ) | $\begin{aligned} & \text { Normal wedge } \\ & \text { angle } \\ & \beta_{\mathrm{ne}}\left(\equiv \beta_{\mathrm{n}}\right) \end{aligned}$ | $\mathrm{A}_{\gamma}$ | $\mathrm{A}_{\alpha}$ | $\mathrm{P}_{\mathrm{n}}\left(\equiv \mathrm{P}_{\mathrm{ne}}\right)$ |

A2. LIST OF SYMBOLS

| SYMBOL | TOOL SURFACES | DEFINITION NO. |
| :---: | :---: | :---: |
| $\mathrm{A}_{\boldsymbol{\gamma}}$ | Face | 4.3.1 |
| $\mathrm{A}_{\alpha}$ | Flank | 4.3.3 |
|  | CUTTING EDGES |  |
| S | Tool major cutting edge | 4.4.1 |
| S' | Tool minor cutting edge | 4.4.1 |
| $\mathrm{S}_{\text {e }}$ | Working major cutting edge | 4.4.1 |
| $S_{\text {e }}{ }^{\prime}$ | Working minor cutting edge | 4.4.1 |
|  | DIMENSIONS |  |
| f | Feed | 4.5.1 |
| $\mathrm{a}_{\mathrm{p}}$ | Back engagement | 4.5.2 |
| $r_{\epsilon}$ | Corner radius | 4.5.3 |
| $\mathrm{b}_{\boldsymbol{\epsilon}}$ | Chamfered corner length | 4.5.4 |
| $\mathrm{b}_{\gamma}$ | Width of land on major face | 4.5.5 |
| $b_{\gamma}{ }^{\prime}$ | Width of land on minor face | 4.5.5 |
| $\mathrm{b}_{\alpha}$ | Width of land on major flank | 4.5.5 |
| $\mathrm{b}_{\alpha}{ }^{\prime}$ | Width of land on minor flank | 4.5.5 |
|  | Note: The number of the land together with the suffix used to identify the plane of measurement may be added. See Table 1. |  |
| $r_{n}$ | Rounded cutting edge radius | 4.5.6 |
|  | TOOL AND WORKPIECE MOTIONS |  |
| $v$ | Cutting speed | 4.6.7 |
| $v_{f}$ | Feed speed | 4.6 .8 |
| $v_{\text {e }}$ | Resultant cutting speed | 4.6 .9 |
| $\phi$ | Feed motion angle | 4.6.10 |
| $\eta$ | Resultant cutting speed angle | 4.6 .11 |
|  | TOOL-IN-HAND REFERENCE SYSTEM OF PLANES |  |
| $\mathrm{P}_{\mathrm{r}}$ | Tool reference plane | 5.2.1 |
| $\mathrm{P}_{\mathrm{f}}$ | Assumed working plane | 5.2.2 |
| $\mathrm{P}_{\mathrm{p}}$ | Tool back plane | 5.2.3 |
| $\mathrm{P}_{\text {s }}$ | Tool cutting edge plane | 5.2.4 |

A2. LIST OF SYMBOLS (Continued)

| SYMBOL | TOOL-IN-HAND REFERENCE SYSTEM OF PLANES (Cont.) | DEFINITION NO. |
| :---: | :---: | :---: |
| $\mathrm{P}_{\mathrm{b}}$$\mathrm{P}_{\mathrm{n}}$ | Tool flank orthogonal plane | 5.2.5 |
|  | Cutting edge normal plane | 5.2.6 |
|  | TOOL-IN-USE REFERENCE SYSTEM OF PLANES |  |
| $\mathrm{P}_{\mathrm{re}}$ | Working reference plane | 5.3.1 |
| $\mathrm{P}_{\mathrm{fe}}$ | Working plane | 5.3.2 |
| $\mathrm{P}_{\mathrm{pe}}$ | Working back plane | 5.3.3 |
| $\mathrm{P}_{\text {se }}$ | Working cutting edge plane | 5.3.4 |
| $\mathrm{P}_{\text {oe }}$ | Working orthogonal plane | 5.3.5 |
| $\mathrm{P}_{\mathrm{ne}} \equiv \mathrm{P}_{\mathrm{n}}$ | Cutting edge normal plane | 5.3.6 |
|  | tool angles |  |
| $\gamma_{n}$ | Tool normal rake | 6.2 .1 |
| $\alpha_{n}$ | Tool normal clearance | 6.2.2 |
| $\alpha_{\text {b }}$ | Tool base clearance | 6.2 .3 |
| $\psi_{\mathrm{r}}$ | Tool lead angle | 6.2.4 |
| $\kappa_{T}$ | Tool cutting edge angle | 6.2.5 |
| $\lambda_{\text {s }}$ | Tool cutting edge inclination | 6.2.6 |
| $\epsilon_{\mathrm{r}}$$\beta_{\mathrm{n}}$ | Tool included angle | 6.2 .7 |
|  | Normal wedge angle | 6.2.8 |
|  | WORKING ANGLES |  |
| $\gamma_{\text {ne }}$ | Working normal rake | 6.3.1 |
| $\alpha_{\text {ne }}$ | Working normal clearance | 6.3.2 |
| $\alpha_{\text {oe }}$ | Working orthogonal clearance | 6.3.3 |
| $\psi_{\text {re }}$ | Working lead angle | 6.3.4 |
| $\kappa_{\text {re }}$ | Working cutting edge angle | 6.3 .5 |
| $\lambda_{\text {se }}$ | Working cutting edge inclination | 6.3.6 |
| $\beta_{\mathrm{ne}} \equiv \beta_{\mathrm{n}}$ | Normal wedge angle | 6.3.7 |

## AMERICAN NATIONAL STANDARDS FOR CUTTING TOOLS




[^0]:    *A third reference system of planes (called the setting system) is required to define the orientation of a cutting tool with respect to the machine tool. This third reference system has still to be defined by the International Standards Organization for this purpose.

[^1]:    *There is some evidence that the "working orthogonal clearance" (6.3.3) is a major factor affecting the rate at which a cutting tool wears on the flank during use. This angle is therefore defined in this standard together with the plane in which it is measured.

[^2]:    *A term used in Great Britain.

[^3]:    *There is some evidence that the "working orthogonal clearance" is a major factor affecting the rate at which a cutting tool wears on the flank during use. This angle is therefore defined in this Standard together with the plane in which it is measured
    **A term used in Great Britain.

